



Use of Computational Fluid Dynamics to Optimize Airflow and Energy Conservation in Laboratory Hoods and Vented Enclosures



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Efficient Operation. Design Goals.

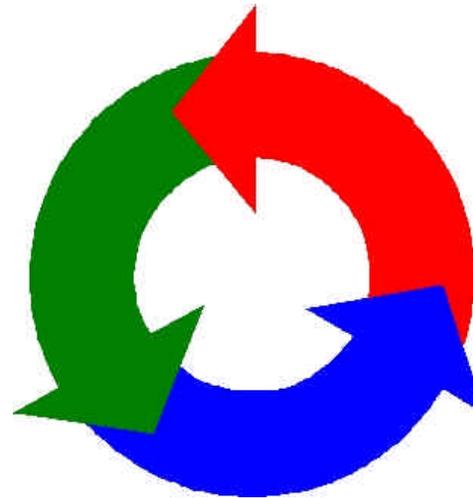
Efficiently operating enclosure must:

- Maintain high level of containment protection
- Provide a steady balance reading
- Ensure that materials inside the enclosure are undisturbed by airflow
- Provide ergonomic design and ensure ease of access
- Address energy efficiency concerns



Task specific custom design loop

Customer requirements



Prototype testing

Airflow modeling and optimization

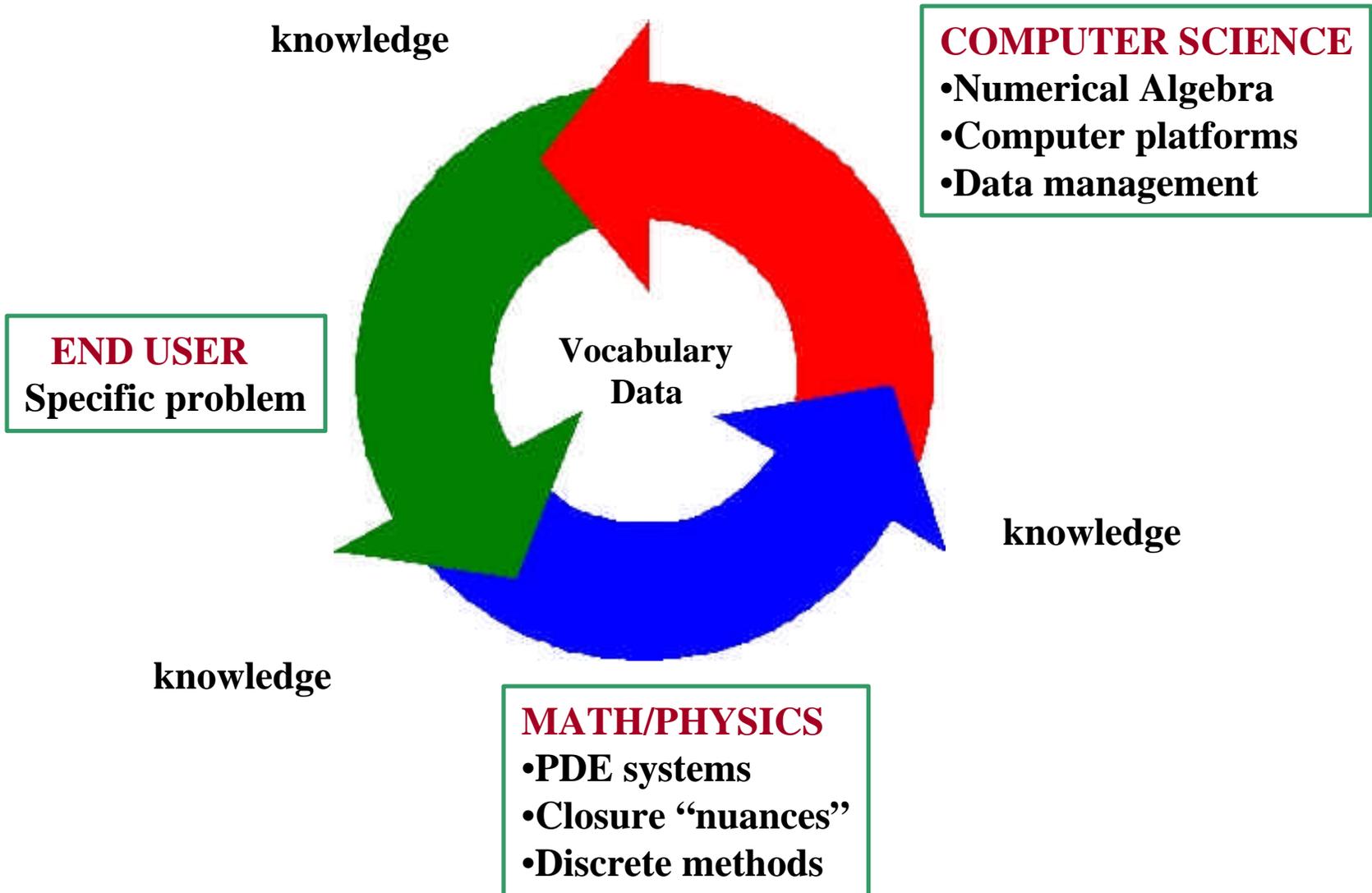
End User Design Goals

Parameters



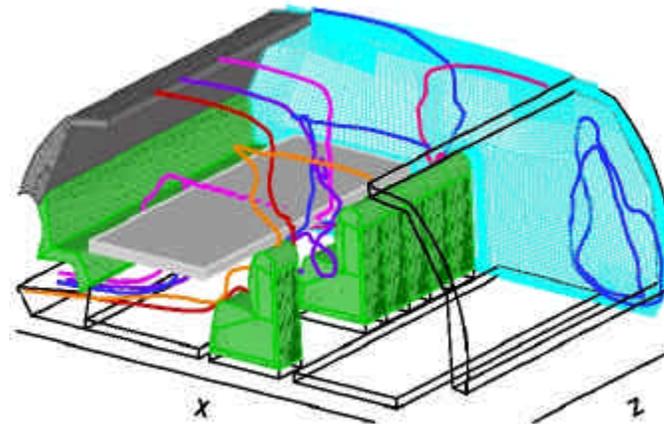
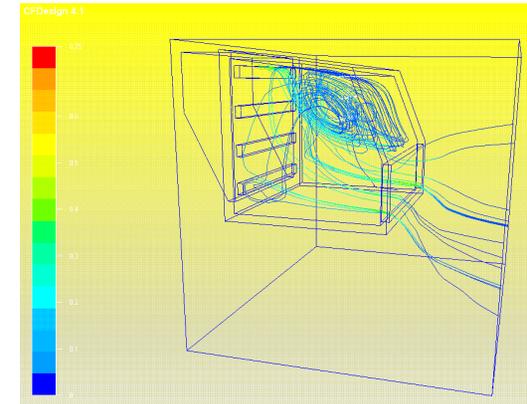
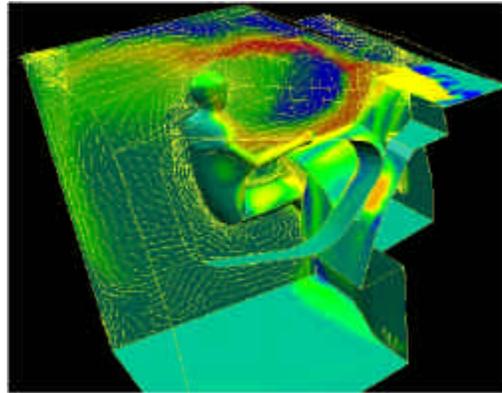
- Turbulence intensity level
- Containment protection
- 1-2' VBSE = 100 CFM air, 1-6' hood = 1200 CFM air
- Energy efficiency, 1200 CFM = \$5K/yr.
- Balance reading stability
- Task specific flexibility
- Ergonomic design, visibility, comfort

CFD Problem Solving Environment



END USER. Applications.

- Aerodynamics
- HVAC
- Air quality
- Automotive
- Turbomachinery
- Combustion
- Electronics



MATH/PHYSICS. PDE Systems I.

Conservation Law System:

Conservation of mass:
$$\frac{1}{r} \frac{\partial r}{\partial t} + \frac{u_j}{r} \frac{\partial r}{\partial x_j} + \frac{\partial u_j}{\partial x_j} = 0$$

Conservation of momentum:
$$r \frac{\partial u_i}{\partial t} + r u_j \frac{\partial u_i}{\partial x_j} - \frac{\partial \mathbf{s}_{ij}}{\partial x_j} - r b_i = 0$$

Conservation of energy:
$$r \frac{\partial e}{\partial t} + r u_j \frac{\partial e}{\partial x_j} - \mathbf{s}_{ij} \mathbf{e}_{ij} - r s + \frac{\partial q_j}{\partial x_j} = 0$$

σ – Cauchy stress tensor, e – internal energy, s – distributed heat generation,
 ϵ - strain-rate tensor, q – heat transfer rate by diffusion.

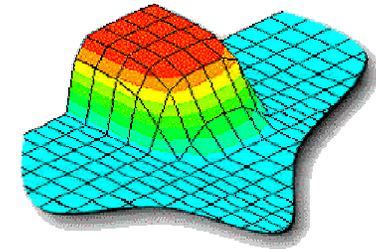
$$\mathbf{e}_{ij} = \frac{1}{2} \left(\frac{\partial u_i}{\partial x_j} + \frac{\partial u_j}{\partial x_i} \right)$$

Math/Physics. Discrete methods.

Spatial discretization:

$$\frac{\partial q}{\partial x_j}, \frac{\partial^2 q}{\partial x_j^2} \rightarrow f(q_{i\pm n, j\pm m, k\pm l})$$

- Finite difference (Taylor series based) methods
- Finite element (weak statement based) methods
- Finite volume methods



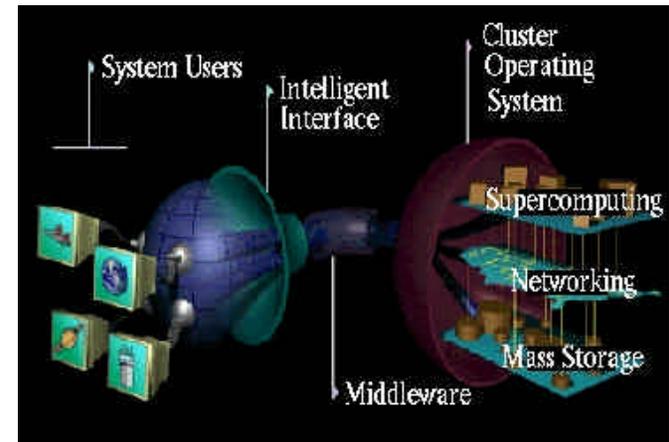
Time – dependent ODE solution methods:

$$\frac{\partial q_{i\pm n, j\pm m, k\pm l}}{\partial t} \rightarrow F(q_{i\pm n, j\pm m, k\pm l}^{p+1, p, p-1})$$

- Single-step
- Multi-step
- Runge-Kutta

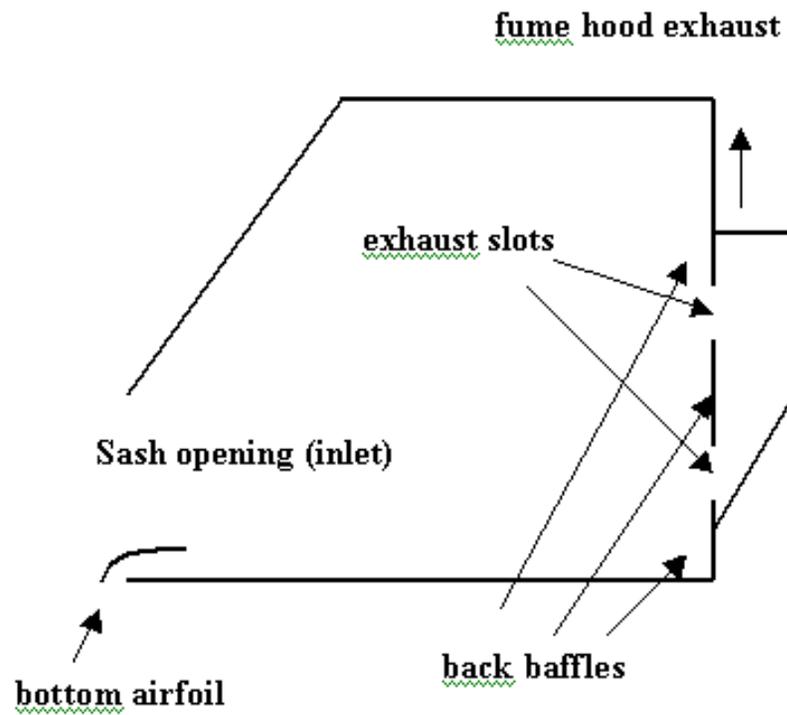
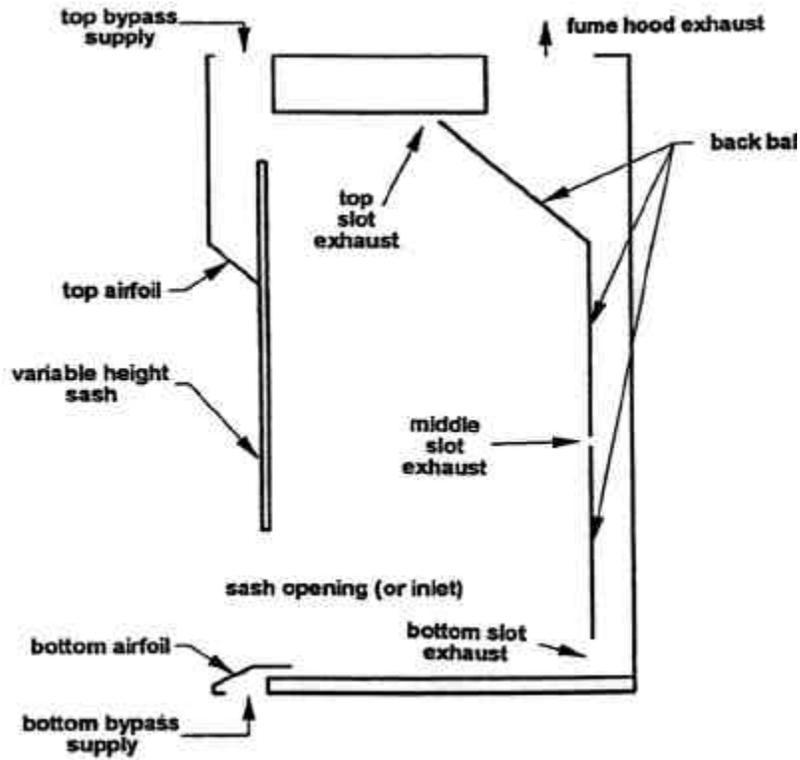
Matrix computation:

- Iterative methods
- $[A]\{x\}=\{b\}$
- Parallel implementation



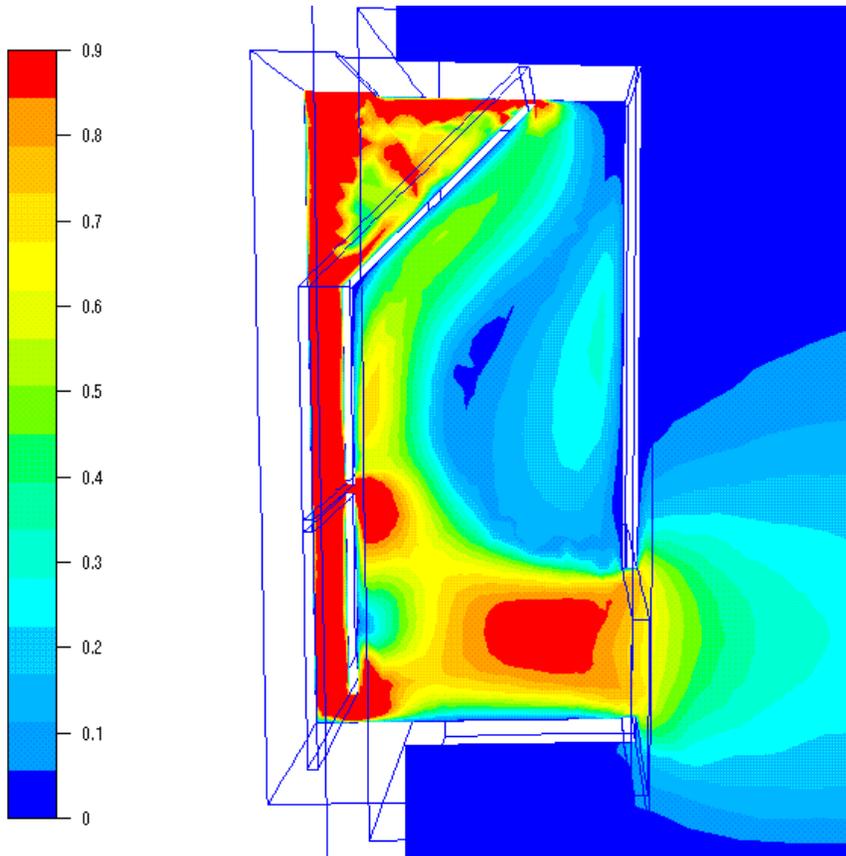
Airflow modeling

General configuration

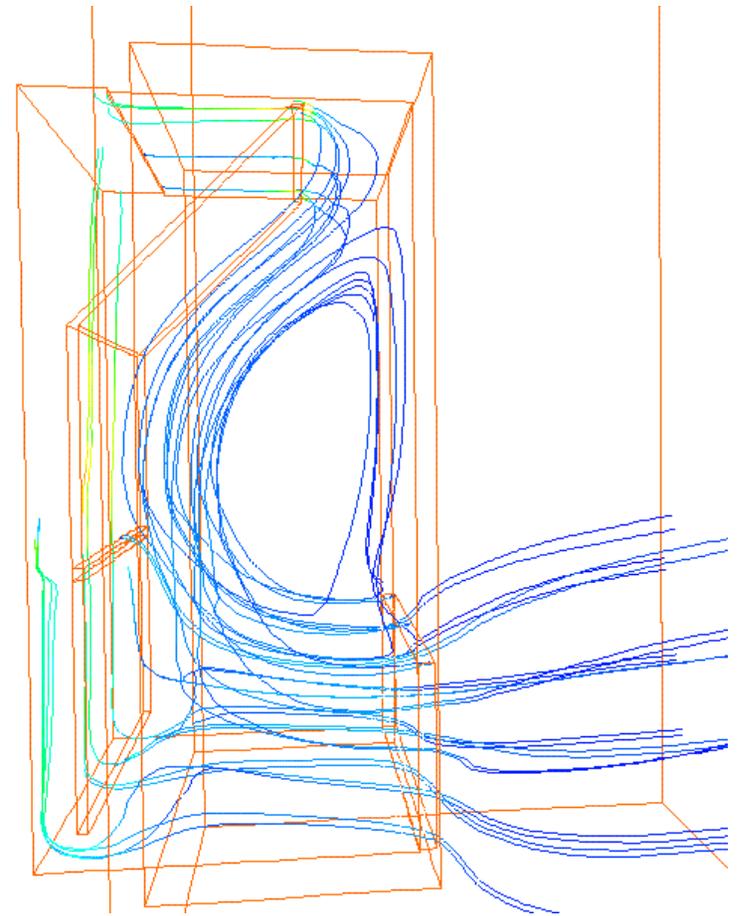


Airflow modeling

Velocity profile



Particle traces



Airflow modeling verification

Literature data

	<i>Experimental flow %</i>	<i>Computational Flow %</i>
<i>Top exhaust</i>	23	24
<i>Middle Exhaust</i>	29	17
<i>Bottom exhaust</i>	48	59

Present research

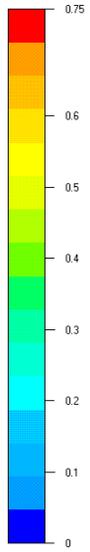
	<i>Experimental flow %</i>	<i>Computational Flow %</i>
<i>Top exhaust</i>	23	21
<i>Middle Exhaust</i>	29	29
<i>Bottom exhaust</i>	48	50

Airflow modeling

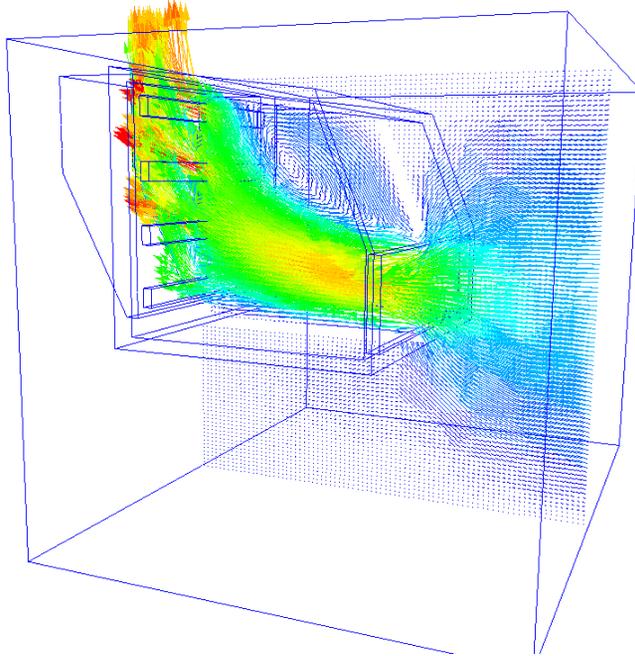
Velocity profile

Particle traces

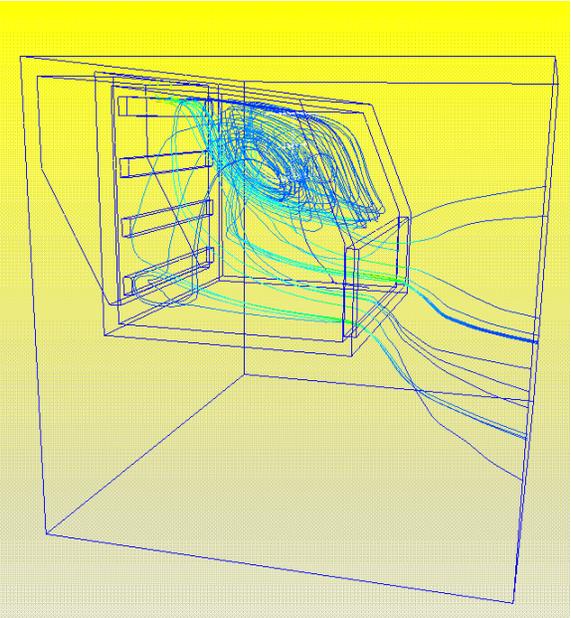
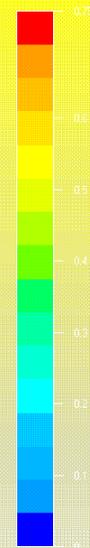
CFDesign 4.1



Iteration 176



CFDesign 4.1

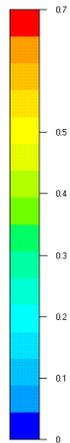


Airflow distribution control

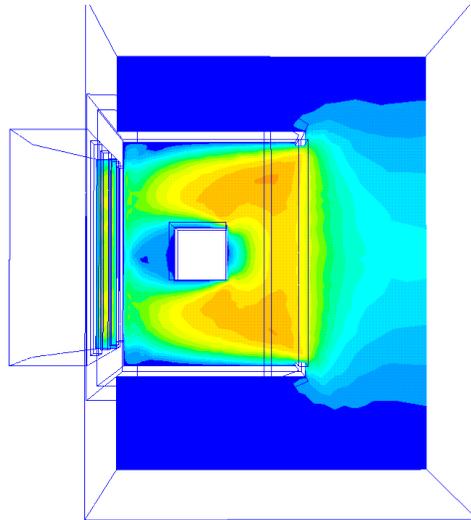
Airflow pattern inside of the enclosure work area is controlled by:

- Geometric configuration
- Sash opening height
- Face velocity
- Operator presence
- Room air currents
- Lab equipment arrangement inside of the work area

CFDesign 4.1

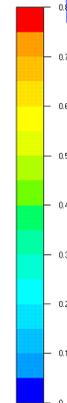


Iteration 100

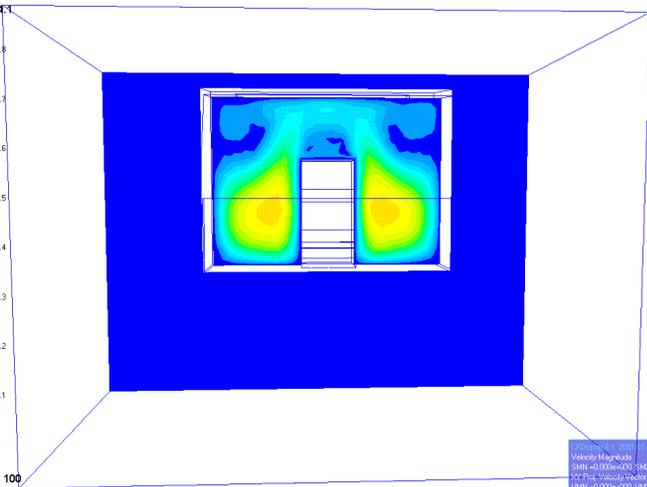


CFDesign 4.1 2009-01-06
Velocity Magnitude
MIN=0.000e+000 MAX=1.150e+000
1/2 Proj. Velocity Vector
VMIN=0.000e+000 VMAX=1.149e+000

CFDesign 4.1



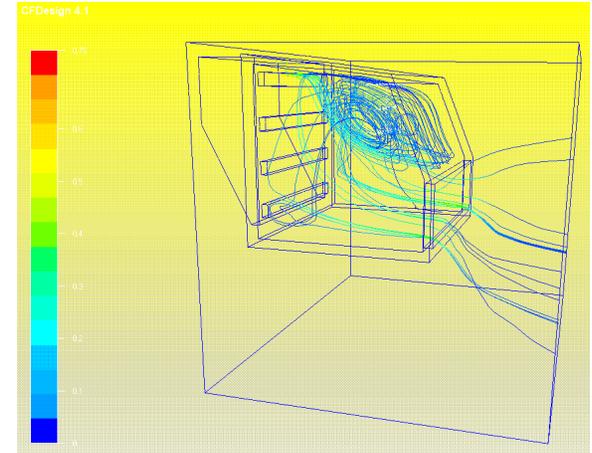
Iteration 100



CFDesign 4.1 2009-01-06
Velocity Magnitude
MIN=0.000e+000 MAX=1.150e+000
1/2 Proj. Velocity Vector
VMIN=0.000e+000 VMAX=1.149e+000

Task Specific Design. Laboratory Enclosure

General work area arrangement



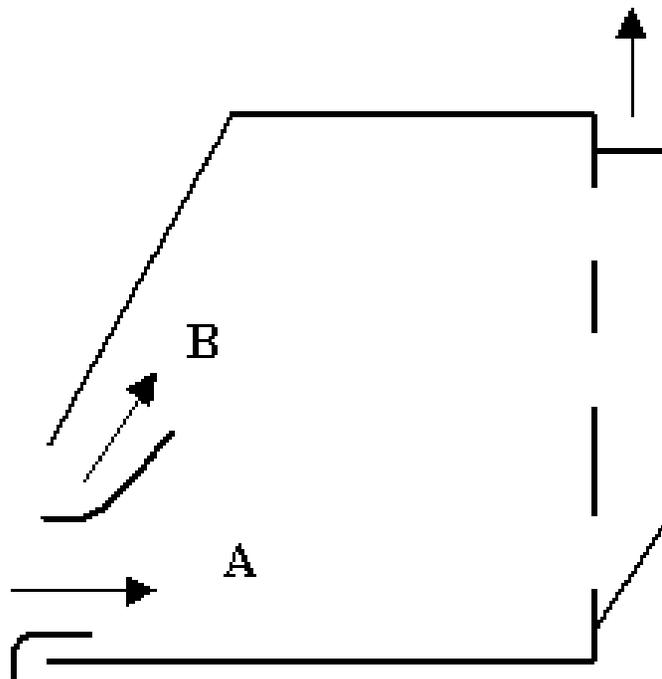
Optimization requirements

- Maximized containment protection
- Potent powder protection
- Ergonomic design
- Work place flexibility
- Energy efficiency

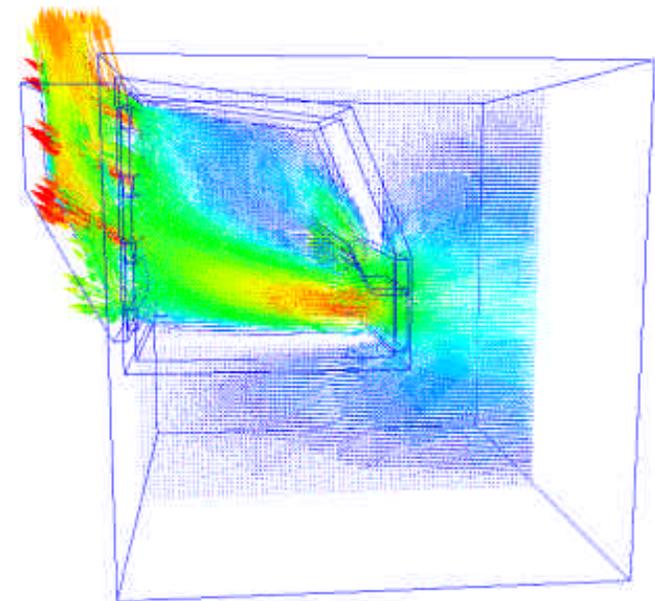
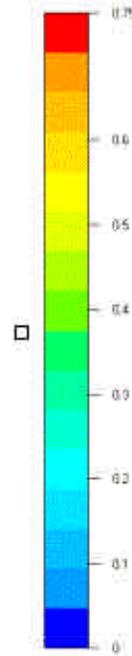
Task Specific Design. Laboratory Enclosure

Proposed solution

- Incoming air is redirected to eliminate the counter-clockwise roll
- Inlet/outlet design is computer controlled and optimized
- Face velocity, work area turbulence minimization
- Smoke/tracer gas testing for prototype optimization



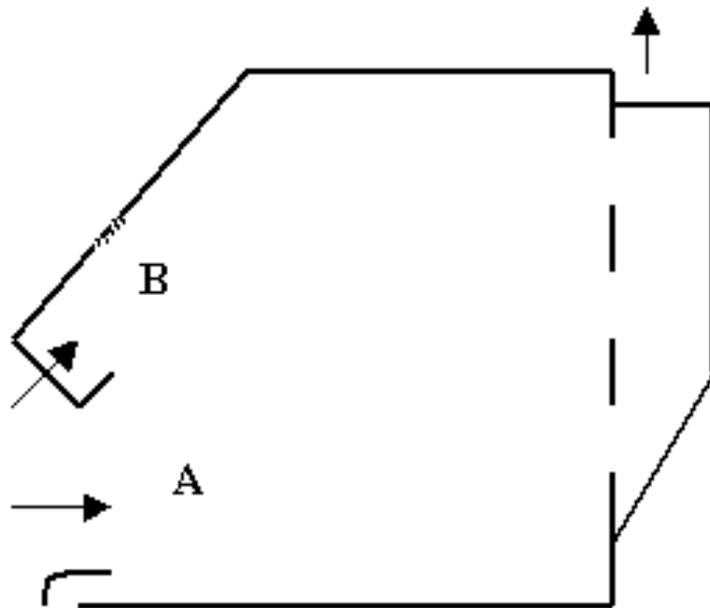
Patent pending



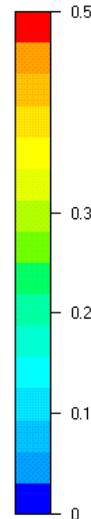
Task specific design. Laboratory enclosure

Proposed solution

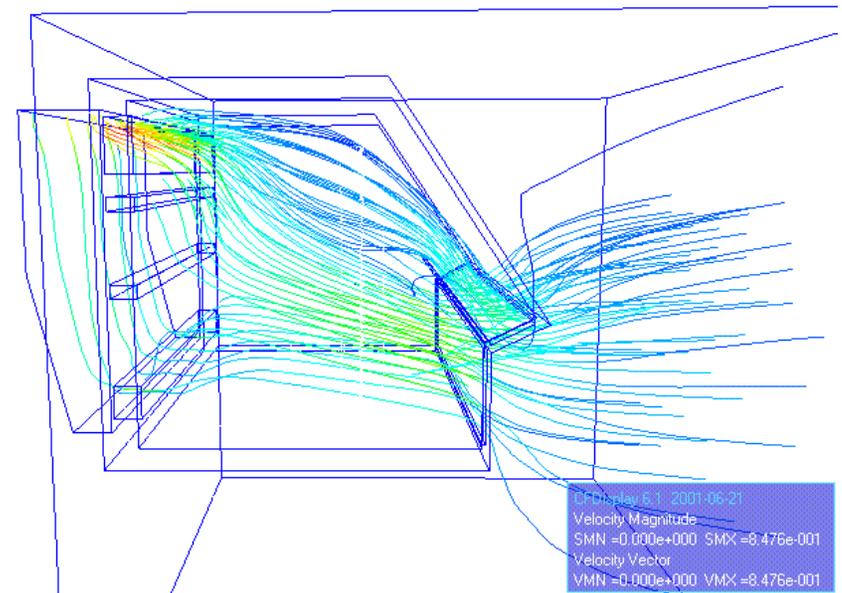
- Maintain high level of containment protection
- Provide a stable balance reading
- Ensure that materials inside the enclosure are undisturbed by airflow
- Provide ergonomic design and ensure ease of access
- Address energy efficiency concerns



CFDesign 4.1



Iteration 49



Patent pending

Task specific design. Robotic enclosure

General work area arrangement

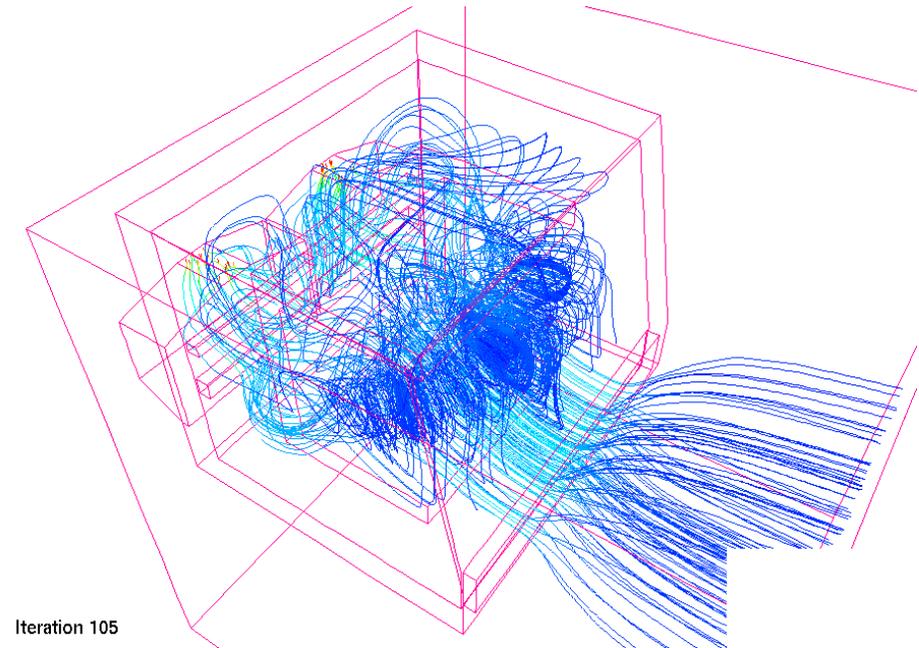
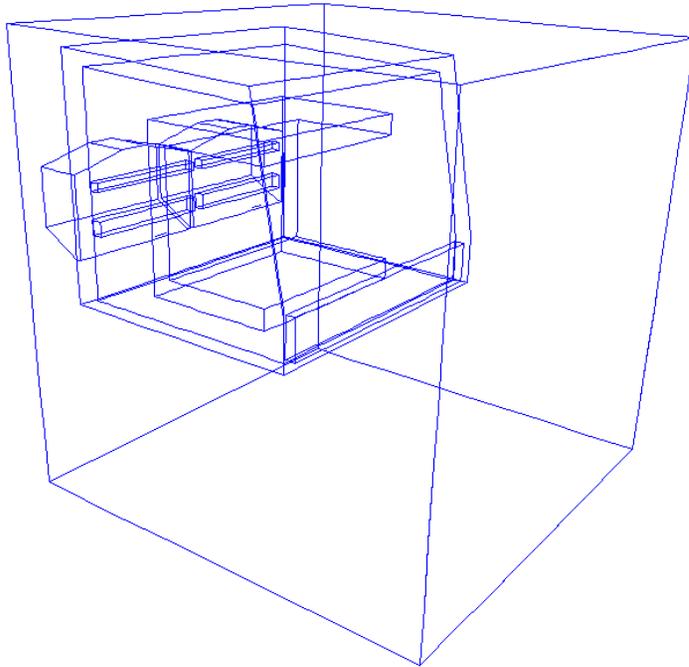


Optimization requirements

- Maintain high level of containment protection, two-mode operation
- Provide a stable balance reading
- Ensure that materials inside the enclosure are undisturbed by airflow
- Provide ergonomic design and ensure ease of access
- Address energy efficiency concerns

Task specific design. Robotic enclosure

Standard design solution

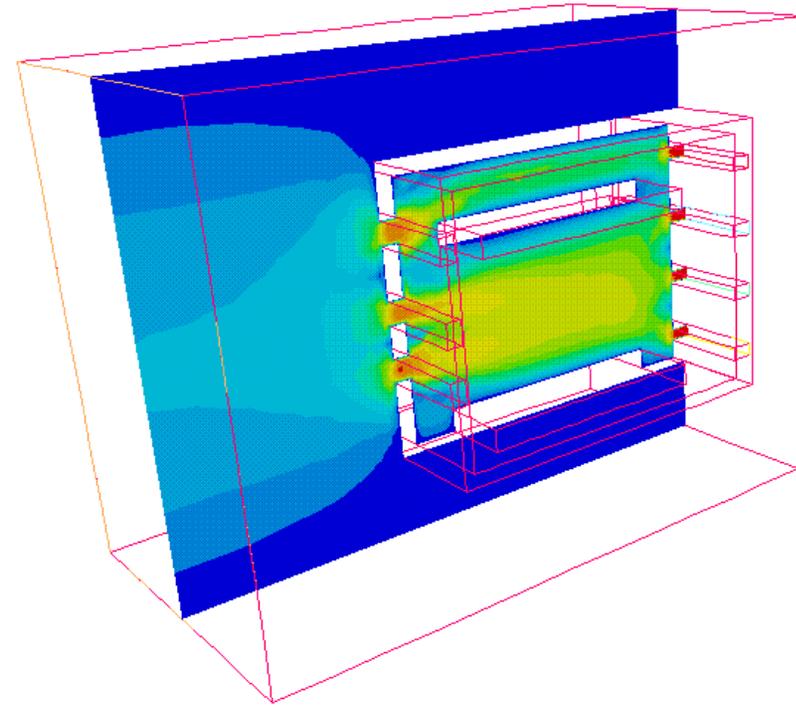
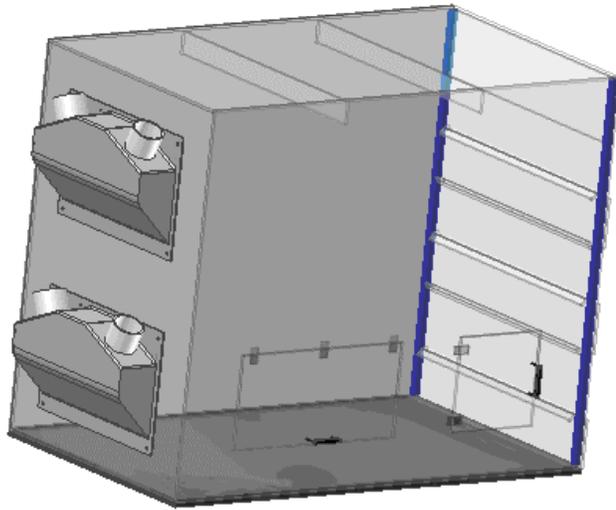


Clearly, there is room for improvement

- High level of work area turbulence
- Ergonomics concerns
- Questionable energy efficiency

Task specific design. Robotic enclosure

Proposed solution



Design improvements

- Low level of work area turbulence
- Ease of access
- Maximized energy efficiency

CFD Simulation.

Navier – Stokes PDE system is not classically solvable!!

CFD simulation protocols are very detailed.

- Mathematics
- Physics
- Discretization
- Computer science

CFD can provide data otherwise absolutely unavailable.

- Repeatability
- Parametric variation
- Density of data

CFD is a two – edged sword.

- Expertise required
- Fundamental knowledge base
- Incredible output detail

